

Lecture 1

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ECE 4950 - Intro to
Quantum Information Science

Statements on quantum computing,
program @ Cornell, other
courses

Requirements for course:

regular homeworks due
every 2 weeks, midterm, &
final exam.

office hours - set up time

QKD - interest

QEC - "

q. chemistry - "

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Review basics of probability theory needed for q. computing.

- Concept of a discrete, finite random variable X , takes values $x \in \mathcal{X}$ w/ probability $P_X(x)$, such that $P_X(x) \geq 0 \quad \forall x \in \mathcal{X}$
 $\& \quad \sum_{x \in \mathcal{X}} P_X(x) = 1.$

- Expected value ^{or mean} of R.V. X is

$$\mu \equiv \mathbb{E}[X] \equiv \mathbb{E}_{P_X}[X] \equiv \sum_{x \in \mathcal{X}} P_X(x) \cdot x$$

Give interpretation ^{later} of why this is expected value.

- Variance is

$$\text{Var}[X] = \sum_{x \in \mathcal{X}} P_X(x) (x - \mu)^2$$

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$$= \mathbb{E}[(X - \mu)^2] = \mathbb{E}[(X - \mathbb{E}[X])^2]$$

can work out that

$$\text{Var}[X] = \mathbb{E}[X^2] - \mu^2$$

Standard deviation:

$$\sigma \equiv \Delta(X) \equiv \sqrt{\text{Var}[X]}$$

measure of the spread about the mean.

Common in complexity theory
& algorithms to consider

a Bernoulli: $R_i V_i$,

which takes value 1 w/

prob. $p \in [0, 1]$ & value 0

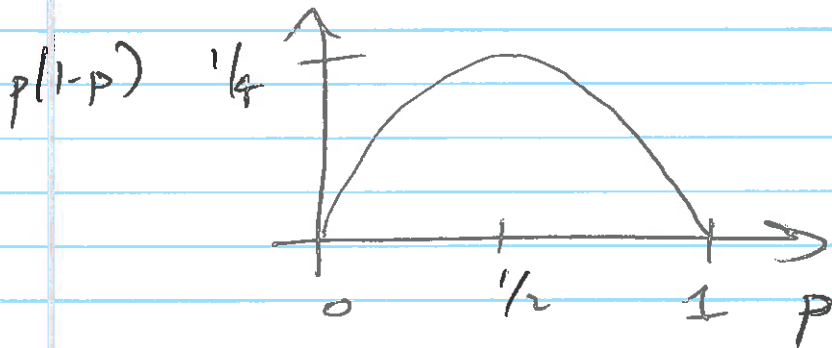
w/ prob. $1-p$.

1 indicates success, while 0
indicates failure.

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What is its mean? p

What is its variance? $p(1-p)$



(most variance
when $p=1/2$)

Why are Bernoulli RVs
important for computation?

Many algorithms output
~~the~~ "yes" or "no" as
an answer.

In randomized algorithms or
quantum algorithms, the
answer is ~~probabilistic~~
correct only w/ some probability.

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Examples of tasks w/ binary outputs:

- 1) binary classification in machine learning (decide cat or dog)
 - 2) Property testing:
decide whether some object has a property or not
decide whether a number is prime
decide if a q . state is entangled
 - 3) decide whether a solution exists to a problem or not
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When an algorithm is probabilistic, how do we gain confidence that an answer is correct?

Repeat the algorithm !!

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When we repeat the algorithm,
we make two assumptions?

- 1) that the Bernoulli RVs
corresponding to each trial
are independent
- 2) that they are identically
distributed

Together these are known as
the i.i.d. assumption

As an example, suppose we have
an algorithm A that decides
whether a positive integer N is
prime & it is correct w/
probability ~~\geq~~ $\geq 2/3$.

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That is, if N is prime,

then A outputs prime w/ prob. $p_1 \geq 2/3$

& if N is not prime,

then A outputs not prime

w/ prob. $p_0 \geq 2/3$.

- Basic idea is that we can invoke the Chernoff bound to ~~prove~~ show that failure probability decreases exponentially fast w/ # of repetitions

- Recall Chernoff bound
independent

Given are n Bernoulli RVs

X_1, \dots, X_T w/ sum $S = \sum_{t=1}^T X_t$

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Then, for $\epsilon \in (0, 1)$

$$\Pr[S \leq (1-\epsilon)\mathbb{E}[S]] \leq e^{-\epsilon^2 \mathbb{E}[S] / 2}$$

How to apply this?

Let A' be modified algorithm
that repeats A T times.

~~It decides prime~~

This leads to Bernoulli RVs

Y_1, \dots, Y_T , Algorithm A'

decides prime if $\sum_{t=1}^T Y_t \geq T/2$

& not prime otherwise.

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Then failure probability is

$$\Pr [A'(N) = \text{not prime} \mid N \text{ is prime}] \\ = \Pr \left[\sum_{t=1}^T Y_t < T/2 \mid N \text{ is prime} \right] (*)$$

Consider that

$$\mathbb{E} \left[\sum_{t=1}^T Y_t \right] = T \cdot p_1 \\ \geq T \cdot \frac{2}{3}$$

Set δ to be such that

$$\frac{T}{2} = (1-\delta) T \cdot \frac{2}{3} \\ \Rightarrow \delta = \frac{1}{4}$$

$$\begin{aligned} \Rightarrow (*) &= \Pr \left[\sum_{t=1}^T Y_t < (1-\delta) T \cdot \frac{2}{3} \mid N \text{ is prime} \right] \\ &\leq \Pr \left[\sum_{t=1}^T Y_t < (1-\delta) T \cdot p_1 \mid N \text{ is prime} \right] \\ &\leq \exp \left(-\delta^2 \cdot T \cdot p_1 / 2 \right) \\ &\leq \exp \left(-\delta^2 T \cdot \frac{2}{3} \cdot 2 \right) \\ &= \exp \left(-T/48 \right) \quad \text{QED} \end{aligned}$$

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We can analyze the failure probability
 $\Pr[A'(N) = \text{prime} \mid N \text{ is not prime}]$

In a similar way by using
the other Chernoff bound

$$\Pr[S \geq (1+\delta)\mathbb{E}[S]] \leq e^{-\delta^2 \mathbb{E}[S]/(2+\delta)}$$

in a similar way (exercise)

Another situation that arises

w/ a probabilistic ~~at~~ or q .

algorithm is when

the algorithm is successful

w/ probability $p \in [0, 1]$ &

there is a way to verify

the answer.

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- For example, if we are trying to factor an integer into a product of primes, we can easily check whether the answer given is correct.
- Another example is in a search task, ~~where~~ ^{in which} we can efficiently check whether a proposed answer is correct.

In this case, we are interested in the number of trials / runs of the algorithm that are necessary until a success occurs.

Such a situation is modeled ⁽¹²⁾
by a geometric random variable

X is geometric if it is equal
to the # of independent
Bernoulli trials needed to
observe one success

$$\Pr[X=k] = (1-p)^{k-1} p$$

(probability to have $k-1$ failures
followed by one success)

$$\mathbb{E}[X] = \frac{1}{p} \quad \text{b/c}$$

$$\mathbb{E}[X] = \sum_{k=1}^{\infty} (1-p)^{k-1} p \cdot k$$

$$= p \sum_{k=1}^{\infty} (1-p)^{k-1} \cdot k$$

$$= p \sum_{k=0}^{\infty} (1-p)^k \cdot k$$

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$$= p \cdot \left(-\frac{d}{dp} \sum_{k=0}^{\infty} (1-p)^k \right)$$

$$= p \cdot \left(-\frac{d}{dp} \frac{1}{p} \right)$$

$$= \frac{1}{p}$$



↳ This is a critical parameter for "repeat until success" algorithms

We are also interested in using randomized or quantum algorithms for estimation tasks.

Given a random variable X (w. prob. dist. $P_X(x)$), we can sample from it & compute the sample mean

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More formally, let X_1, \dots, X_n be i.i.d. samples of X .

Sample mean is

$$\bar{X}_n = \frac{1}{n} \sum_{i=1}^n X_i$$

Hoeffding bound guarantees that

$$\Pr[|\bar{X}_n - \mathbb{E}[X]| \leq \epsilon] \geq 1 - \delta$$

where $\epsilon, \delta \in (0, 1)$,
as long as

$$n \geq \frac{M^2}{2\epsilon^2} \ln\left(\frac{2}{\delta}\right)$$

where $M = b - a$ if each X takes values on finite interval $[a, b]$.

gives a guarantee on sample complexity of algorithm