

Lecture 6

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Semidefinite programming (SDP)

AKA semidefinite optimization

important class of optimization

problems that arise in QIT.

Many bounds on rates of

communication can be phrased

as SDPs

- useful as numerical &

analytical tool (perhaps one

of the most important tools

in modern QIT)

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Φ is a Hermiticity preserving superoperator if $\Phi(X)$ is Hermitian whenever X is.

SDP: Input: Hermitian operators $A \dagger B \dagger$
Hermiticity preserving superop. Φ

primal SDP: $\sup_{X \geq 0} \{ \text{Tr}[AX] : \Phi(X) \leq B \}$
 $\equiv S(\Phi, A, B)$

$X \geq 0 \dagger \Phi(X) \leq B$ are

operator inequalities,

meaning that X is PSD

$\dagger B - \Phi(X)$ is PSD

directly relevant to QIT,

we'll learn that states satisfy

$X \geq 0 \dagger \text{Tr}[X] = 1$ \dagger measurement operators satisfy $\Lambda \geq 0 \quad \Lambda \leq I$

(3)

related to the primal SDP,
there is a dual SDP, in
which the objective function
& constraint are "flipped"
as well as the optimization

dual SDP:

$$\hat{S}(\Phi, A, B) = \inf_{Y \succeq 0} \{ \text{Tr}[BY] : \Phi^+(Y) \succeq A \}$$

Φ^+ is adjoint of Φ

$$\text{(i.e., } \text{Tr}[Y + \Phi(X)] =$$

$$\text{Tr}[\Phi^+(Y) + X] \quad \forall X, Y)$$

X is called primal feasible

if $\Phi(X) \preceq B$ & $X \succeq 0$

Y is dual feasible if

$$\Phi^+(Y) \succeq A \quad \& \quad Y \succeq 0$$

(4)

There may not exist primal feasible
or dual feasible operators.

If no primal feasible exists,
then $S(\Phi, A, B) = -\infty$

If no dual feasible, then

$$\hat{S}(\Phi, A, B) = +\infty$$

Weak duality

$$S(\Phi, A, B) \leq \hat{S}(\Phi, A, B)$$

always holds!

proof is simple:

Let $X, Y \geq 0$ be feasible.

$$\begin{aligned} \text{then } \text{Tr}[AX] &\leq \text{Tr}[\Phi + (Y)X] = \text{Tr}[Y\Phi(X)] \\ &\leq \text{Tr}[YB] \end{aligned}$$

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Since these inequalities hold

\forall feasible X, Y

\Rightarrow

$$\sup_{\substack{\text{primal} \\ X \text{ feasible}}} \text{Tr}[AX] \leq \inf_{\substack{Y \text{ dual} \\ \text{feas.}}} \text{Tr}[BY]$$

\square

connection between weak
duality & max-min inequality

$$\left(\begin{array}{l} \sup_Y \inf_X F(X, Y) \\ \leq \inf_X \sup_Y F(X, Y) \end{array} \right)$$

Consider Lagrangian

$$\mathcal{L} \equiv \mathcal{L}(\Phi, A, B, X, Y)$$

$$= \text{Tr}[AX] + \text{Tr}[BY] - \text{Tr}[\Phi(X)\Psi]$$

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can rewrite as

$$\begin{aligned} \mathcal{L} &= \text{Tr}[AX] + \text{Tr}[(B - \Phi(x))Y] \\ &= \text{Tr}[BY] + \text{Tr}[(A - \Phi^T(Y))X] \end{aligned}$$

First take inf over $Y \succeq 0$ †

then sup over $X \succeq 0$

$$\Rightarrow = \sup_{X \succeq 0} \inf_{Y \succeq 0} \text{Tr}[AX] + \text{Tr}[(B - \Phi(x))Y]$$

$$(\star) = \sup_{X \succeq 0} \left(\text{Tr}[AX] + \inf_{Y \succeq 0} \text{Tr}[(B - \Phi(x))Y] \right)$$

↑
focus on this
term

Suppose that $B \not\geq \Phi(x)$
(constraint violated)

⑦

then $B - \Phi(x)$ not PSD
+ $\exists |\psi\rangle$ such that

$$\langle \psi | B - \Phi(x) | \psi \rangle < 0$$

Pick $Y = c |\psi\rangle\langle\psi|$

for $c > 0$

+ then $\text{Tr}[(B - \Phi(x)) Y]$
 $= \text{Tr}[(B - \Phi(x)) c |\psi\rangle\langle\psi|]$
 $= c \langle \psi | B - \Phi(x) | \psi \rangle$

By taking $c \rightarrow +\infty$, we get

$$\inf_{Y \geq 0} \text{Tr}[(B - \Phi(x)) Y] = -\infty$$

So we find that

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$$\begin{aligned} (*) &= \sup_{X \succeq 0} \{ \text{Tr}[AX] : \Phi(X) \leq B \} \\ &= S(\Phi, A, B) \end{aligned}$$

Similarly,

$$\inf_{Y \succeq 0} \sup_{X \succeq 0} \mathcal{L} = \hat{S}(\Phi, A, B)$$

$$\text{Since } \sup_{X \succeq 0} \inf_{Y \succeq 0} \mathcal{L} \leq \inf_{Y \succeq 0} \sup_{X \succeq 0} \mathcal{L}$$

this is the same as
weak duality

strong duality is when

the opposite inequality holds
can check using Slater's condition
conclude that

$$S(\Phi, A, B) = \hat{S}(\Phi, A, B) \text{ in this case}$$

Slater's condition

④

sufficient condition for strong duality

if $\exists X \succ 0$ such that $\Phi(X) \leq B$

and $\exists Y \succ 0$ such that

$$\Phi^*(Y) > A$$

then $S = S^*$ and \exists primal feasible

X for which $\text{Tr}\{AX\} = S(\Phi, A, B)$

alternative condition to check

w/ non-strict and strict inequalities
switched.

Complementary Slackness

helpful for understanding constraints
on optimal X and Y .

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~~For every~~

Consider an SDP corresp. to Φ, A, B + suppose strong duality holds.

Then the following conditions hold for feasible X & Y iff they are optimal:

$$YB = Y\Phi(X)$$

$$\Phi^+(Y) X = AX$$

Proof:

Recall inequalities for weak duality

$$\text{Tr}[AX] \leq \text{Tr}[\Phi^+(Y)X] = \text{Tr}[Y\Phi(X)] \leq \text{Tr}[BY]$$

if strong duality holds for optimal X & Y , then these are all equalities,

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$$\Rightarrow \text{Tr}[(\Phi^+(y) - A) X] = 0$$

$$\& \text{Tr}[(B - \Phi(x)) Y] = 0$$

since operators involved are PSD

then conclude

$$(\Phi^+(y) - A) X = 0 \quad \&$$

$$(B - \Phi(x)) Y = 0 \quad \Rightarrow \text{statement}$$

Now suppose c.s. equations hold.

then inequalities are saturated
& operators are thus optimal.