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Lecture 7

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Composite Noisy Quantum Systems

Suppose two independent ensembles for Alice & Bob

- Alice has $\{p_X(x), |\psi_x\rangle\}$
- Bob has $\{p_Y(y), |\phi_y\rangle\}$

For given x, y , state is $|\psi_x\rangle \otimes |\phi_y\rangle$

density operator of joint system is

$$\begin{aligned} & \mathbb{E}_{x,y} \{ (|\psi_x\rangle \otimes |\phi_y\rangle) (\langle\psi_x| \otimes \langle\phi_y|) \} \\ &= \mathbb{E}_{x,y} \{ |\psi_x\rangle \langle\psi_x| \otimes |\phi_y\rangle \langle\phi_y| \} \\ &= \sum_{x,y} p_X(x) p_Y(y) |\psi_x\rangle \langle\psi_x| \otimes |\phi_y\rangle \langle\phi_y| \\ &= \left(\sum_x p_X(x) |\psi_x\rangle \langle\psi_x| \right) \otimes \left(\sum_y p_Y(y) |\phi_y\rangle \langle\phi_y| \right) \quad (\text{TP 3 linear}) \\ &= \rho \otimes \sigma \end{aligned}$$

↑
product state

(similar to independent distributions)

$$p(x) \rightarrow X \rightarrow |\psi_x\rangle$$

$$p(y) \rightarrow Y \rightarrow |\phi_y\rangle$$

Separable States

generate a correlated ensemble

$$\{P_X(x), |\psi_x\rangle \otimes |\phi_x\rangle\}$$

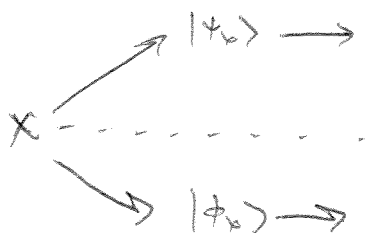
density operator is

$$\sum_x P_X(x) |\psi_x\rangle\langle\psi_x| \otimes |\phi_x\rangle\langle\phi_x|$$

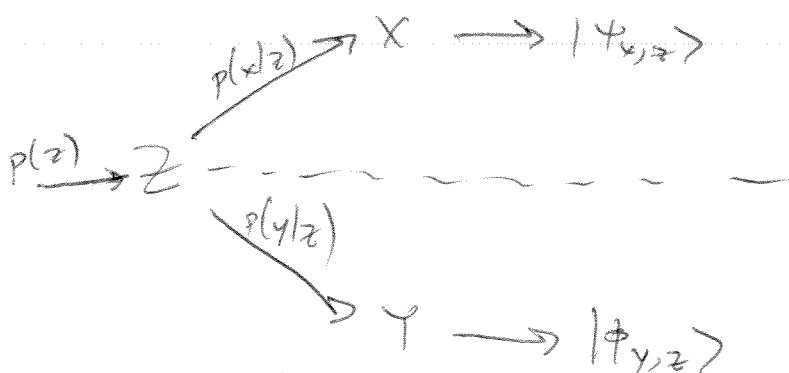
local density operators are

$$\sum_x P_X(x) |\psi_x\rangle\langle\psi_x| \quad \& \quad \sum_x P_X(x) |\phi_x\rangle\langle\phi_x|$$

picture is



can have further mixing



$$P_Z(z) \rightarrow \{P_{X|Z}(x|z), |\psi_{x,z}\rangle\}$$

state is

$$\{P_{Y|Z}(y|z), |\phi_{y,z}\rangle\}$$

$$\sum_z P_Z(z) P_Z \otimes \sigma_z$$

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Local Density Operator

Suppose global state of Alice & Bob is

$$|\Phi^+\rangle_{AB} = \frac{1}{\sqrt{2}} (|00\rangle_{AB} + |11\rangle_{AB})$$

Would like to consider probabilities if Alice performs local measurement w/ measurement operators $\{M_m\}$ where ~~$\sum_m M_m = I$~~

global measurement operators are $\{M_m^A \otimes I^B\}$
Then probability for outcome m is

$$\begin{aligned} \text{Tr} \{ (M_m^A \otimes I^B) |\Phi^+\rangle \langle \Phi^+| \} &= \langle \Phi^+ | M_m^A \otimes I^B | \Phi^+ \rangle \\ &= \frac{1}{2} \sum_{i,j=0}^1 \langle i^A | \langle i^B | (M_m^A \otimes I^B) | j^A | j^B \rangle \\ &= \frac{1}{2} \sum_{i,j=0}^1 \langle i^A | M_m^A | j^A \rangle^A \langle i^B | j^B \rangle^B \\ &= \frac{1}{2} \sum_{i=0}^1 \langle i | M_m | i \rangle \\ &= \frac{1}{2} \sum_{i=0}^1 \text{Tr} \{ M_m |i\rangle \langle i| \} \\ &= \text{Tr} \{ M_m \pi \} \end{aligned}$$

$$\text{where } \pi \equiv \frac{1}{2} (|0\rangle \langle 0| + |1\rangle \langle 1|)$$

local measurements give same results as if state is totally random...

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local measurement results are the same
as for the state

$$\pi_A \otimes \pi_B$$

\Rightarrow can only distinguish these states w/
global measurements (no-clone problem)

Partial Trace

- would like to determine a local density
operator that ~~predicts~~ gives probabilities
for outcomes of all local measurements

- can use partial trace - suppose state is

$$\begin{aligned} \text{Tr}_Y \{ |x\rangle\langle x|^X \otimes |y\rangle\langle y|^Y \} &= |x\rangle\langle x|^X \text{Tr} \{ |y\rangle\langle y|^Y \} \\ &= |x\rangle\langle x|^X \langle y|y\rangle \\ &= |x\rangle\langle x|^X \end{aligned}$$

In general, mathematical definition is

$$\text{Tr}_2 \{ |x_1\rangle\langle x_2| \otimes |y_1\rangle\langle y_2| \} = |x_1\rangle\langle x_2| \langle y_1|y_2\rangle$$

acts linearly.

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example for ^{arbitrary} density operator

$$\rho^{AB}$$

expand in terms of some basis $|i\rangle^A \otimes |j\rangle^B$
for joint system

$$\begin{aligned} \rho^{AB} &= \sum_{ijkl} \rho_{ijkl} (|i\rangle^A \otimes |j\rangle^B) (\langle k|^A \otimes \langle l|^B) \\ &= \sum_{ijkl} \rho_{ijkl} |i\rangle \langle k|^A \otimes |j\rangle \langle l|^B \end{aligned}$$

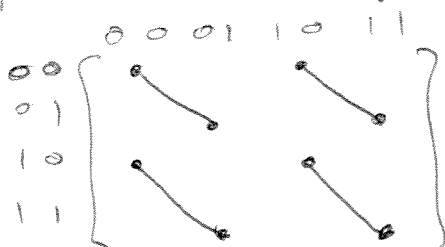
can now do partial trace

$$\begin{aligned} \rho^A &= \text{Tr}_B \left\{ \sum_{ijkl} \rho_{ijkl} |i\rangle \langle k|^A \otimes |j\rangle \langle l|^B \right\} \\ &= \sum_{ijkl} \rho_{ijkl} |i\rangle \langle k|^A \langle l|j\rangle \end{aligned}$$

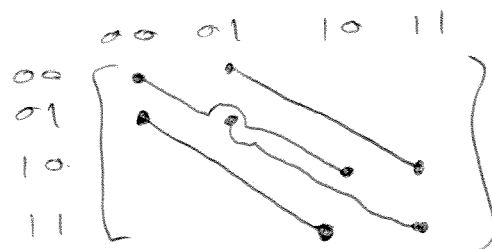
$$= \sum_{ijk} \rho_{ijkj} |i\rangle \langle k|$$

$$= \sum_{ik} \left(\sum_j \rho_{ijkj} \right) |i\rangle \langle k|$$

partial trace over 2nd system



partial trace over 1st system



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can show that "local" quantum theory is
consistent w/ "global" quantum theory

$$\text{Tr} \left\{ (U_m^A \otimes I^B) \rho^{AB} \right\} = \text{Tr} \left\{ U_m^A \rho^A \right\}$$

(HWK)

can also show that full trace is
composed of partial traces

$$\begin{aligned} \text{Tr} \left\{ M^{AB} \right\} &= \text{Tr}_A \left\{ \text{Tr}_B \left\{ M^{AB} \right\} \right\} \\ &= \text{Tr}_B \left\{ \text{Tr}_A \left\{ M^{AB} \right\} \right\} \end{aligned}$$

Classical - Quantum Ensemble

consider ensemble

$$\left\{ p_X(x), |x\rangle \right\}$$

if it is $\left\{ p_X(x), |x\rangle \right\}$, then density operator

$$\rho = \sum_x p_X(x) |x\rangle \langle x| \quad \downarrow \text{ can learn}$$

about distribution $p_X(x)$ by performing

measurements of the system

$$\left\{ |x\rangle \langle x| \right\}$$

(need many "copies" of this
ensemble)

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In general, ensemble is $\{p_x(x), \rho_x\}$

& density operator is $\sum_x p_x(x) \rho_x$

difficult to learn about $p_x(x)$ if states ρ_x are mixed.

Alice can solve this problem by correlating a classical state w/ ρ_x so that enlarged ensemble is

$$\{p_x(x), |x\rangle\langle x|^X \otimes \rho_x^A\}$$

classical-quantum ensemble (cq ensemble)

b/c 1st system classical & second system quantum

density operator of enlarged ensemble is

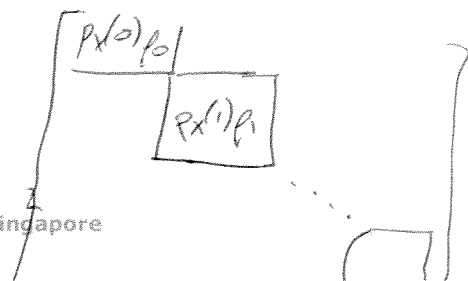
$$\rho^{XA} \equiv \sum_x p_x(x) |x\rangle\langle x|^X \otimes \rho_x^A$$

can perform measurement on X to learn about $p_x(x)$

can perform measurement on A to learn about $\rho = \sum_x p(x) \rho_x$

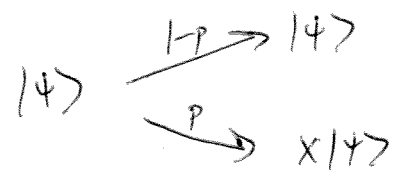
can perform joint measurement to learn about $\{p_x(x), \rho_x\}$

Also, $\rho^{XA} = \bigoplus p_x(x) \rho_x^A =$



Noisy Evolution

Suppose state is $|\psi\rangle$. send over bit-flip channel.

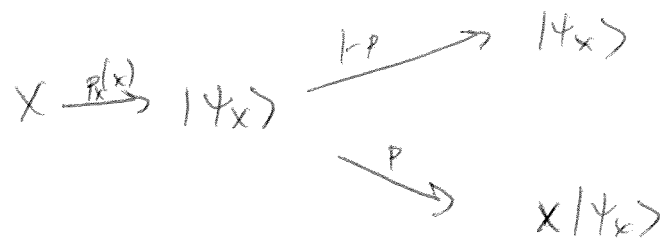


ensemble is $\{ \{p, X|\psi\rangle\}, \{1-p, |\psi\rangle\} \}$

density operator is

$$p X|\psi\rangle\langle\psi|X + (1-p)|\psi\rangle\langle\psi|$$

ensemble is $\{ p_X(x), |\psi_x\rangle \}$. send through channel



ensemble is $\{ \{p_X(x)p, X|\psi_x\rangle\}, \{p_X(x)(1-p), |\psi_x\rangle\} \}$

density operator is

$$\sum_x p_X(x) [p X|\psi_x\rangle\langle\psi_x|X + (1-p)|\psi_x\rangle\langle\psi_x|]$$

$$= p X\rho X + (1-p)\rho$$

state is more mixed than original state
(can quantitatively show this later on)

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in general, random unitary channel is

$$\sum_K p(k) U_k \rho U_k^\dagger$$

Losing Information from Measurement

$$\{P_x(x), |\psi_x\rangle\}$$

measurement operators $\{M_k\}$ such that $\sum_K M_k^\dagger M_k = I$

Suppose know state. probability of outcome k is

$$P_{K|X}(k|x) = \langle \psi_x | M_k^\dagger M_k | \psi_x \rangle$$

post-measurement state is

$$\frac{M_k |\psi_x\rangle}{\sqrt{P_{K|X}(k|x)}}$$

~~ensemble~~ suppose we lose track of measurement outcome

ensemble is then

$$\left\{ P_{X|K}(x|k) P_K(k), \frac{M_k |\psi_x\rangle}{\sqrt{P_{K|X}(k|x)}} \right\}$$

density operator is

$$\sum_{x,k} P_{K|X}(k|x) P_X(x) \frac{M_k |\psi_x\rangle \langle \psi_x| M_k^\dagger}{P_{K|X}(k|x)} = \sum_K M_k \rho M_k^\dagger = \mathcal{N}(\rho)$$

11/25/2011 evolution is trace-preserving

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$$\begin{aligned}\text{Tr} \left\{ \sum_K M_K \rho M_K^\dagger \right\} &= \text{Tr} \left\{ \sum_K M_K^\dagger M_K \rho \right\} \\ &= \text{Tr} \left\{ \rho \right\} = 1\end{aligned}$$

Examples of Noisy Channels

Dephasing $\rho \rightarrow (1-p)\rho + p Z \rho Z$

action on Bloch Vector is

$$\begin{aligned}(1-p) \left[\frac{1}{2} (\mathbb{I} + r_x X + r_y Y + r_z Z) \right] + \\ p \left[\frac{1}{2} Z (\mathbb{I} + r_x X + r_y Y + r_z Z) Z \right] \\ = \frac{1}{2} \left[\mathbb{I} + r_x (1-2p) X + r_y (1-2p) Y + r_z Z \right]\end{aligned}$$

compresses along X + Y directions while preserving

Z direction. for sending classical info,

encode in Z direction $\{|0\rangle, |1\rangle\}$

similar behavior for

$$\rho \rightarrow (1-p)\rho + p Y \rho Y$$

+

$$\rho \rightarrow (1-p)\rho + p X \rho X$$

complete dephasing is same as forgetting out some of Z measurement,