

Lecture 19

2 APR 2014

①

With the error reduction technique from before, there are two undesirable aspects:

- 1) we need many copies of the quantum proof or witness
- 2) the quantum proof is damaged

Remarkably, there is a way around both of these problems due to an approach by Marriott & Watrous detailed in [arxiv:cs/0506068](https://arxiv.org/abs/cs/0506068).

To motivate this approach,

consider a QMA proof system

w/ perfect completeness, so that

for all $x \in A_{\text{yes}}$, \exists a state $|\psi\rangle$ such

that $\Pr\{\text{accept}(x, \psi)\} = 1$ &

$\forall x \in A_{\text{no}} + |\psi\rangle$, $\Pr\{\text{accept}(x, \psi)\} \leq 1/3$

(2)

$$\text{Let } \Pi_1 = |1\rangle\langle 1| \otimes I_{p(n)+n-1}$$

"projection onto the accepting subspace"

$$\Pi_0 = |0\rangle\langle 0| \otimes I_{p(n)+n-1}$$

"projection onto the rejecting subspace"

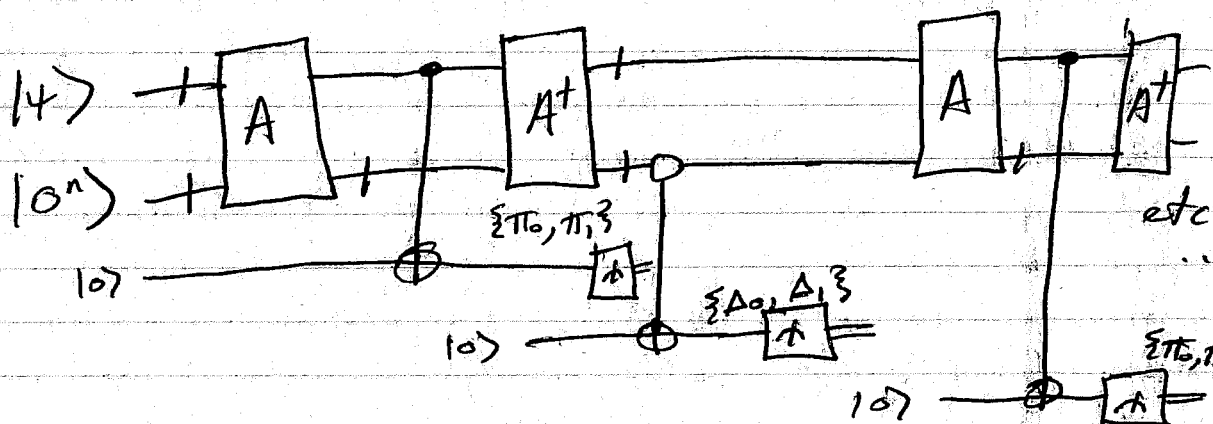
$$\Delta_1 = I_{p(n)} \otimes |0^n\rangle\langle 0^n|$$

"projection onto the valid input subspace"

$$\Delta_0 = I_{p(n)+n} - \Delta_1$$

"projection onto the invalid input subspace"

Consider the following circuit



idea is

apply A , measure $\{\Pi_0, \Pi_1\}$,
apply A^\dagger , measure $\{\Delta_0, \Delta_1\}$,
~~repeat~~ repeat...

3

In the case of a YES instance, (assuming perfect completeness), we always get "1" as the measurement outcome. This is b/c the 1st measurement accepts w/ probability 1 & also, this measurement does not disturb the state at all. Then ~~when~~ the 2nd measurement will give 1 always, etc.

On the other hand, for a NO instance, the 1st measurement is successful only w/ $\text{pr} \{ \cdot \} \leq 1/3$, implying that the witness state is potentially damaged. Further measurements then do not succeed perfectly, the probability of accepting will fall off exponentially w/ the # of repetitions.

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Now, QMA w/ perfect completeness is not known to be equal to QMA, so we need a different procedure to reduce error for QMA proof systems w/o perfect completeness.

For this purpose, we will use the same quantum procedure w/ a different classical post-processing.

We know that the maximum acceptance probability of the proof system is

$$\begin{aligned} & \max_{|\psi\rangle} \left\| \Pi_1 A |\psi\rangle |0^n\rangle \right\|_2^2 \\ &= \max_{|\psi\rangle} \left\| \Pi_1 A \Delta_1 |\psi\rangle |0^n\rangle \right\|_2^2 \\ &= \max_{|\psi\rangle} \langle \psi | \langle 0^n | \Delta_1 A^\dagger \Pi_1 A \Delta_1 |\psi\rangle |0^n\rangle \\ &= \max_{|\psi\rangle} \langle \phi | \Delta_1 A^\dagger \Pi_1 A \Delta_1 |\phi\rangle \\ &= \left\| \Delta_1 A^\dagger \Pi_1 A \Delta_1 \right\|_\infty \equiv P \end{aligned}$$

(5)

So the best strategy of the prover
is to supply $|\phi\rangle = |\psi\rangle|0^n\rangle$.

We want to figure out the form
of the post-measurement states
after every measurement.

So after 1st iteration, the states
will be

$$|\gamma_0\rangle \equiv \frac{\pi_0 A \Delta_1 |\phi\rangle}{\sqrt{1-p}}$$

$$|\gamma_1\rangle \equiv \frac{\pi_1 A \Delta_1 |\phi\rangle}{\sqrt{p}}$$

We know that $\langle \gamma_1 | \gamma_0 \rangle = 0$ b/c

$$\pi_0 \pi_1 = 0$$

Furthermore

$$\langle \gamma_1 | \gamma_1 \rangle = \frac{1}{p} \langle \phi | \Delta_1 A^\dagger \pi_1 A \Delta_1 | \phi \rangle$$

$$= \frac{p}{p} \langle \phi | \phi \rangle$$

$$= 1$$

($|\phi\rangle$ is an eigenvector
of

$\Delta_1 A^\dagger \pi_1 A \Delta_1$
w/ eigenval.
p)

so $|\gamma_1\rangle$ is a unit vector

(6)

Also

$$\begin{aligned}
\langle \gamma_0 | \gamma_0 \rangle &= \langle \phi | \Delta_1 A^\dagger \Pi_0 A \Delta_1 | \phi \rangle / (1-p) \\
&= \langle \phi | \Delta_1 A^\dagger \underbrace{(\mathbb{I} - \Pi_1)}_{1-p} A \Delta_1 | \phi \rangle \\
&= \frac{1-p}{1-p} \langle \phi | \phi \rangle \\
&= 1
\end{aligned}$$

so $|\gamma_0\rangle$ is also a unit vector

$\Rightarrow \{|\gamma_0\rangle, |\gamma_1\rangle\}$ is an o.n. basis

The next step of the procedure is to apply A^\dagger after ~~me~~ applying A & measuring $\{\Pi_0, \Pi_1\}$, so we want to know the form of

$$A^\dagger |\gamma_0\rangle \text{ \& \ } A^\dagger |\gamma_1\rangle$$

~~We~~ We will return to this question after a little development

(7)

$$\text{Let } |\delta_1\rangle = \frac{\Delta_1 A^\dagger \Pi_1 |\chi_1\rangle}{\sqrt{p}}$$

$$|\delta_0\rangle = \frac{\Delta_0 A^\dagger \Pi_1 |\chi_1\rangle}{\sqrt{1-p}}$$

$$\text{Then } \langle \delta_1 | \delta_0 \rangle = 0 \quad \text{b/c} \quad \Delta_1 \Delta_0 = 0$$

$$\text{Also, } |\delta_1\rangle = |\phi\rangle \quad \text{b/c}$$

$$|\delta_1\rangle = \frac{\Delta_1 A^\dagger \Pi_1 |\chi_1\rangle}{\sqrt{p}}$$

$$= \left(\frac{\Delta_1 A^\dagger \Pi_1}{\sqrt{p}} \right) \left(\frac{\Pi_1 A \Delta_1}{\sqrt{p}} \right) |\phi\rangle$$

$$= \frac{1}{p} \Delta_1 A^\dagger \Pi_1 A \Delta_1 |\phi\rangle$$

$$= \frac{p}{p} |\phi\rangle = |\phi\rangle \quad \text{b/c } |\phi\rangle$$

is an
eigenvector
of
 $\Delta_1 A^\dagger \Pi_1 A \Delta_1$

Furthermore, $|\chi_1\rangle$ is an eigenvector
of $\Pi_1 A \Delta_1 A^\dagger \Pi_1$ w/ eigenval. p b/c

$$\begin{aligned} \Pi_1 A \Delta_1 A^\dagger \Pi_1 |\chi_1\rangle &= \Pi_1 A \Delta_1 A^\dagger \Pi_1 \left(\frac{\Pi_1 A \Delta_1 |\phi\rangle}{\sqrt{p}} \right) \\ &= \Pi_1 A \Delta_1 \frac{p}{\sqrt{p}} |\phi\rangle \end{aligned}$$

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$$= p \left(\frac{\Pi_1 A \Delta_1}{\sqrt{p}} |\phi\rangle \right) = p |\gamma_1\rangle$$

All of this implies that

$$\begin{aligned} \langle \delta_1 | \delta_1 \rangle &= \frac{1}{p} \langle \gamma_1 | \Pi_1 A \Delta_1 A^\dagger \Pi_1 | \gamma_1 \rangle \\ &= \frac{p}{p} \langle \gamma_1 | \gamma_1 \rangle \\ &= 1 \end{aligned}$$

$|\delta_1\rangle$ is a unit vector

By similar reasoning

$$\begin{aligned} \langle \delta_0 | \delta_0 \rangle &= \frac{1}{1-p} \langle \gamma_1 | \Pi_1 A \Delta_0 A^\dagger \Pi_1 | \gamma_1 \rangle \\ &= \frac{1}{1-p} \langle \gamma_1 | \Pi_1 A (I - \Delta_1) A^\dagger \Pi_1 | \gamma_1 \rangle \\ &= \frac{1-p}{1-p} \langle \gamma_1 | \gamma_1 \rangle = 1 \end{aligned}$$

so $|\delta_0\rangle$ is a unit vector

$\Rightarrow \{ |\delta_0\rangle, |\delta_1\rangle \}$ is an o.n. basis

So if we get $|\gamma_1\rangle$ after the first measurement, apply A^\dagger ,

followed by a measurement of $\{ \Delta_0, \Delta_1 \}$ we get post-measurement states $|\delta_0\rangle$ & $|\delta_1\rangle$

(9)

Now if we get $|s_1\rangle$ & apply A ,
what is the form of $A|s_1\rangle$?

Consider that

$$\begin{aligned} A|s_1\rangle &= (\pi_0 + \pi_1) A|s_1\rangle \\ &= \pi_0 A|s_1\rangle + \pi_1 A|s_1\rangle \end{aligned}$$

$$= \pi_0 A \Delta_1 \frac{A^\dagger \pi_1}{\sqrt{p}} |\gamma_1\rangle +$$

$$\pi_1 A \Delta_1 \frac{A^\dagger \pi_1}{\sqrt{p}} |\gamma_1\rangle$$

$$= \pi_0 A \Delta_1 \frac{A^\dagger \pi_1 A \Delta_1}{\sqrt{p} \cdot \sqrt{p}} |\phi\rangle$$

$$+ \frac{p}{\sqrt{p}} |\gamma_1\rangle$$

$$= \pi_0 A |\phi\rangle + \sqrt{p} |\gamma_1\rangle$$

$$= \sqrt{1-p} |\gamma_0\rangle + \sqrt{p} |\gamma_1\rangle$$

Since $\{|s_0\rangle, |s_1\rangle\}$ is an O.N. basis

& A is unitary, $A|s_0\rangle$ has
the form

$$A|s_0\rangle = -\sqrt{p} |\gamma_0\rangle + \sqrt{1-p} |\gamma_1\rangle$$

So this is

$$A |s_1\rangle = \sqrt{1-p} |s_0\rangle + \sqrt{p} |s_1\rangle$$

$$A |s_0\rangle = -\sqrt{p} |s_0\rangle + \sqrt{1-p} |s_1\rangle$$

Applying A^\dagger to this gives

$$|s_1\rangle = \sqrt{1-p} A^\dagger |s_0\rangle + \sqrt{p} A^\dagger |s_1\rangle$$

$$|s_0\rangle = -\sqrt{p} A^\dagger |s_0\rangle + \sqrt{1-p} A^\dagger |s_1\rangle$$

Multiply 1st by $\sqrt{1-p}$ + 2nd by \sqrt{p}

$$\sqrt{1-p} |s_0\rangle = -\sqrt{p(1-p)} A^\dagger |s_0\rangle + (1-p) A^\dagger |s_1\rangle$$

$$\sqrt{p} |s_1\rangle = \sqrt{p(1-p)} A^\dagger |s_0\rangle + p A^\dagger |s_1\rangle$$

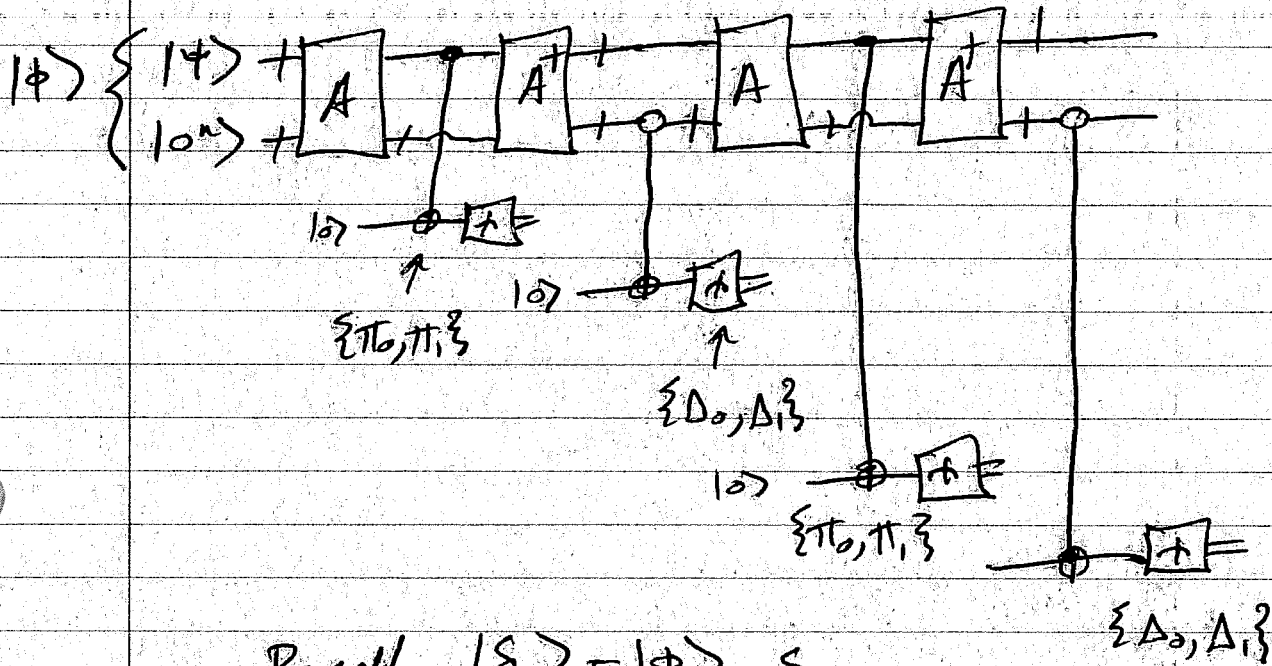
Add them to find that

$$A^\dagger |s_1\rangle = \sqrt{1-p} |s_0\rangle + \sqrt{p} |s_1\rangle$$

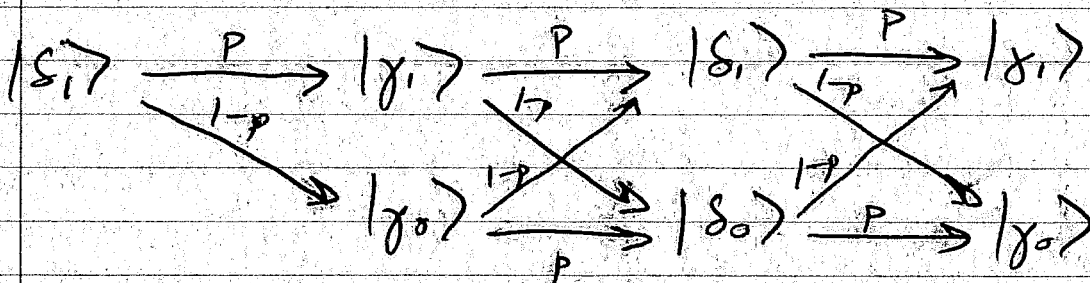
$$A^\dagger |s_0\rangle = -\sqrt{p} |s_0\rangle + \sqrt{1-p} |s_1\rangle$$

(1)

Now, from these equations we can say what happens from the following circuit:



Recall $|\delta_1\rangle = |\psi\rangle, s.$



~~So the probability of any~~
 Idea is to keep track of each transition,
 i.e., whether one measurement outcome
 is different from the previous.

(12)

Let y_i denote the outcome of the i^{th} measurement, w/ $y_0 = 1$ since we start w/ $|\delta_1\rangle$ as the initial state

Then set

$$z_i = \begin{cases} 1 & \text{if } y_i = y_{i-1} \\ 0 & \text{if } y_i \neq y_{i-1} \end{cases}$$

The probability for any particular sequence z is

$$z^N = (z_1, \dots, z_N)$$

$$p^{w(z^N)} (1-p)^{N-w(z^N)}$$

where w counts the number of ones.

Then we compute

$$\frac{1}{N} \sum_{i=1}^N z_i \quad \& \quad \text{accept if this is larger than } \frac{a+b}{2}$$

We know that $p \geq a$ in the case of a YES instance, while $a - \frac{a+b}{2} = \frac{a-b}{2} = \frac{1}{2} \epsilon(n)$

(13)

So using Chernoff bound as before,
~~we get~~ of setting $N = 8q^2(n) r(n)$

for $r \in \text{poly}$
the probability of acceptance is
larger than $1 - 2^{-r(n)}$

Also, as a bonus, observe that
we get the witness back after
about $O(\frac{1}{p^2})$ repetitions
of the procedure.

For the case of a NO instance,
we need to use the fact that

H(4) $\Pr \{ \text{accept}(x, t) \} \leq b(n)$

of any (4) can be written in
the eigenbasis of $\Delta, A^\dagger \Pi, A \Delta,$

of a fact from linear algebra known
as Jordan's lemma & Chernoff bound
to conclude that

$\frac{a+b}{2} \geq b$

$\frac{a+b}{2} - b = \frac{a-b}{2}$

$\Pr \{ \text{accept} \} \leq 2^{-r(n)}$