

Lecture 15

19 MAR 2014

Continue w/ Grover's algorithm...

The action of U_R on an arbitrary state is to perform an "inversion about the mean", i.e.,

for a state $\sum_x \alpha_x |x\rangle$

the mean amplitude is $\frac{1}{2^n} \sum_x \alpha_x = \mu$

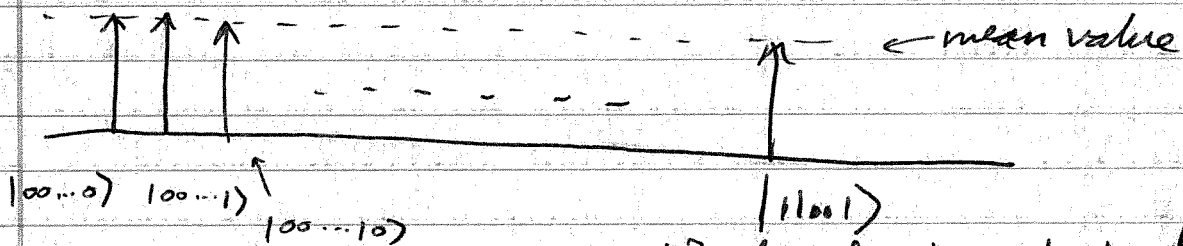
So, we calculate

$$\begin{aligned} U_R \sum_x \alpha_x |x\rangle &= \\ &= (2|t\rangle\langle t| - I) \sum_x \alpha_x |x\rangle \\ &= \left(\frac{2}{2^n} \sum_{y,z} |y\rangle\langle z| - I \right) \left(\sum_x \alpha_x |x\rangle \right) \\ &= \frac{2}{2^n} \sum_{y,z,x} \alpha_x |y\rangle\langle z|x\rangle - \sum_x \alpha_x |x\rangle \\ &= \frac{2}{2^n} \sum_y \left(\sum_z \alpha_z \right) |y\rangle - \sum_x \alpha_x |x\rangle \\ &= \sum_x (2\mu - \alpha_x) |x\rangle \end{aligned}$$

2

Grover's algorithm only uses real amplitudes, so we can visualize it more easily.

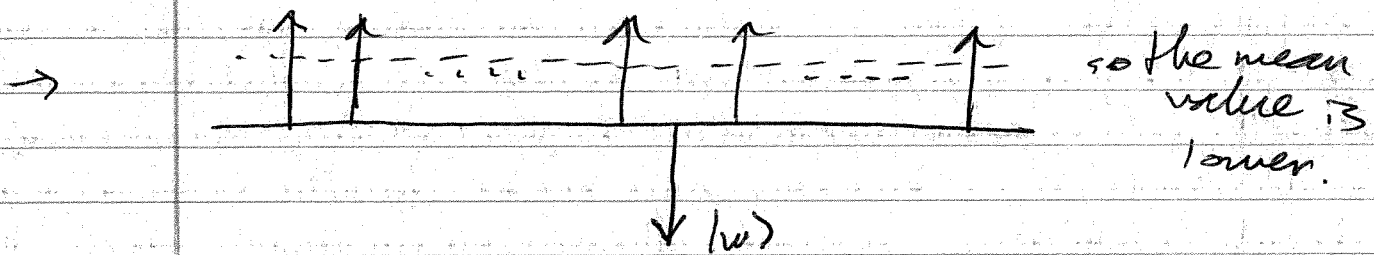
Initially the state is a uniform superposition looking like



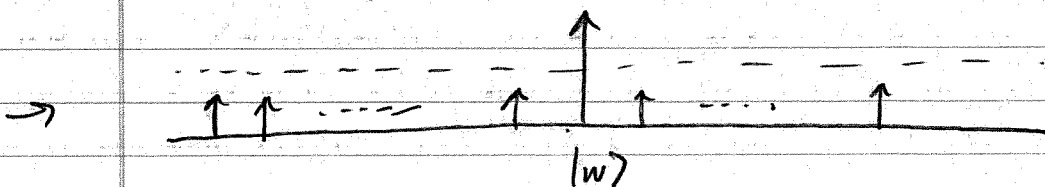
amplitude for target is $\frac{1}{\sqrt{N}}$

Now apply U_f

desired state will get inverted about 0.



Now apply U_R (inversion about the mean)



Amplitude of $|w\rangle$ increases by about $\frac{2}{\sqrt{N}}$ & all other amplitudes go down. The idea is to iterate this procedure about $O(\sqrt{N})$ times to have ~~the~~ nearly all of the ^{amplitude} weight on the solution.

Keep repeating this & we add roughly $\frac{2}{\sqrt{N}}$ to the amplitude of $|w\rangle$ on each iteration.

For an analysis, it suffices to consider the 2D subspace spanned by

$$\{|w\rangle, |t_{\text{bad}}\rangle\}$$

The initial state is

$$|t_0\rangle = \frac{1}{\sqrt{N}} |w\rangle + \sqrt{\frac{N-1}{N}} |t_{\text{bad}}\rangle$$

Another basis for this subspace is

$$\{|t_0\rangle, |t_n\rangle\}$$

4

where

$|f_n\rangle$ is orthogonal to $|t_n\rangle$, i.e.,

$$|f_n\rangle = \sqrt{\frac{N-1}{N}} |w\rangle - \frac{1}{\sqrt{N}} |t_{bad}\rangle$$

Let θ be such that

$$\sin \theta = \frac{1}{\sqrt{N}} \quad \neq$$

$$\cos \theta = \sqrt{\frac{N-1}{N}} .$$

So

$$|t_n\rangle = \sin \theta |w\rangle + \cos \theta |t_{bad}\rangle$$

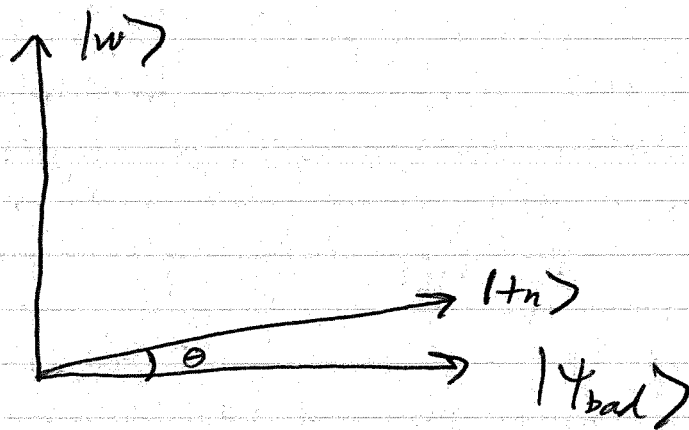
$$|f_n\rangle = \cos \theta |w\rangle - \sin \theta |t_{bad}\rangle$$

Also

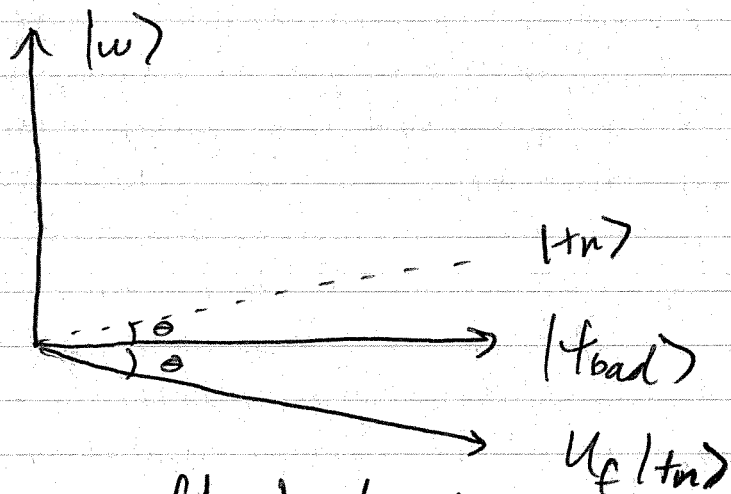
$$|w\rangle = \sin \theta |t_n\rangle + \cos \theta |f_n\rangle$$

$$|t_{bad}\rangle = \cos \theta |t_n\rangle - \sin \theta |f_n\rangle$$

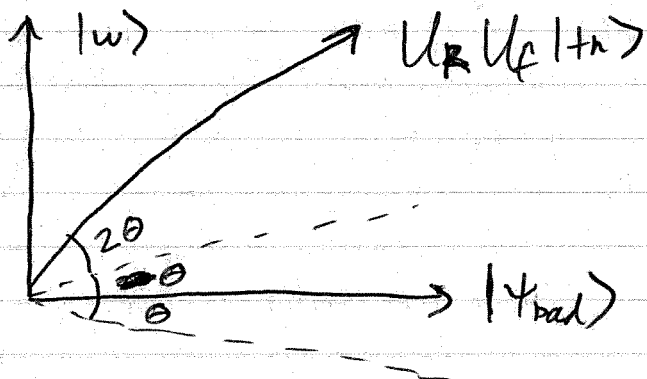
Initial picture:



U_f can be thought of as a reflection about $|tbad\rangle$. This gives



Next, we reflect about $|tn\rangle$, giving



(6)

So after the Grover iterate,
~~we~~ the state becomes

$$\sin(2\theta + \theta) |w\rangle + \cos(2\theta + \theta) |w_{\text{bad}}\rangle$$

Continuing this idea, after k
Grover iterates, the state becomes

$$\sin((2k+1)\theta) |w\rangle + \cos((2k+1)\theta) |w_{\text{bad}}\rangle$$

So, in order to have a high
probability of measuring $|w\rangle$
when performing a measurement
of the 1st register, we would like
to have

$$\sin((2k+1)\theta) \approx 1$$

which means that

$$(2k+1)\theta \approx \pi/2 \text{ \& thus}$$

$$k \approx \frac{\pi}{4\theta} - \frac{1}{2} \approx \frac{\pi}{4} \sqrt{N} = O(\sqrt{N})$$

(using $\sin\theta \approx \theta$ for large N)