

## Lecture 19

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Stinespring dilation theorem for Gaussian channels:

- Any Gaussian channel can be realized by the action of a Gaussian unitary ~~act~~ on the input state & an environment prepared in a Gaussian state.
- Also, any Gaussian unitary that interacts the system w/ a Gaussian environment state leads to a Gaussian channel w/  $X$  &  $Y$  satisfying

$$iX \Omega_n X^T + Y \succeq i \Omega_m$$

(1a)

Note that this condition implies that  $Y \succeq 0$ .

let  $\psi$  be a real  $2m \times 1$  vector. Then

$$iX \Lambda_n X^T + Y - i\Lambda_m \succeq 0$$

$$\Rightarrow \psi^T (iX \Lambda_n X^T + Y - i\Lambda_m) \psi \geq 0$$

$$\Rightarrow i(X^T \psi)^T \Lambda_n (X^T \psi) + \psi^T Y \psi - i\psi^T \Lambda_m \psi \geq 0$$

$$\Rightarrow \psi^T Y \psi \geq 0 \quad \forall \psi$$

$$\Rightarrow Y \succeq 0.$$

(2)

Let us establish the 2nd statement first.

Let  $S$  be a symplectic matrix such that

$$S = \begin{bmatrix} \overset{2n}{\underbrace{A}} & \overset{2l}{\underbrace{B}} \\ \underbrace{C} & \underbrace{D} \end{bmatrix} \begin{matrix} \} 2m \\ \} 2(n+l-m) \end{matrix}$$

where  $n$  is # of input modes,

$m$  is # of output modes,

&  $l$  is # of environment modes.

Since  $S$  is symplectic,

$A, B, C,$  &  $D$  satisfy

$$\Lambda_{n+l} = S \Lambda_{n+l} S^T$$

$$= \left[ \begin{array}{c|c} A \Lambda_n A^T + B \Lambda_l B^T & A \Lambda_n C^T + B \Lambda_l D^T \\ \hline C \Lambda_n A^T + D \Lambda_l B^T & C \Lambda_n C^T + D \Lambda_l D^T \end{array} \right]$$

③

$$= \begin{bmatrix} \Lambda_m & 0 \\ 0 & \Lambda_{n+l-m} \end{bmatrix}$$

We get the action of the channel by tracing out the  $n+l-m$  output environment modes, i.e., by considering the upper left  $2m \times 2m$  block of

$$S(\sigma \oplus \sigma_E)S^T$$

where  $\sigma_E$  is the covariance matrix for the initial state of the environment.

The matrix  $\sigma_E$  is thus constrained to satisfy  $\sigma_E + i\Lambda_e \geq 0$  ( $\Leftrightarrow \sigma_E \geq i\Lambda_e$ )

$\Rightarrow$  output state cov. matrix is given by  $A\sigma A^T + B\sigma_E B^T$

(4)

Then  $\sigma_E + i\Lambda_e \geq 0$

$$\Rightarrow B\sigma_E B^T + iB\Lambda_e B^T \geq 0$$

Using the constraint

$$B\Lambda_e B^T = \Lambda_m - A\Lambda_n A^T$$

$$\Rightarrow B\sigma_E B^T + i\Lambda_m - iA\Lambda_n A^T \geq 0$$

Identify  $X = A$  &

$$Y = B\sigma_E B^T \quad \dagger$$

connect w/ previous  
description of a Gaussian  
channel.

then this implements a Gaussian  
channel according to the  
previous definition.

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Now let us prove the other direction:

Given  $2m \times 2n$  real matrix  $X$

&  $2m \times 2m$  real symmetric  $Y$

satisfying

$$iX \Omega_n X^\dagger + Y \geq i \Omega_m$$

$\exists$  a Gaussian unitary  $U$

s.t.

$$N(\rho) = \text{Tr}_E [ U (\rho \otimes |0\rangle\langle 0|) U^\dagger ]$$

For covariance matrices,  
evolution  $\beta$  is given by

$$\sigma \rightarrow X \sigma X^\dagger + Y$$

↑  
where this  
 $\beta$  is a tensor  
-power  
vacuum  
state

(6)

We want to find symplectic

$$\text{matrix } S = \begin{bmatrix} A & B \\ C & D \end{bmatrix}$$

such that  $A = X$

Initial state of environment will  
be tensor-power vacuum

w/ C.M.  $\sigma_E = I$ , ( $2l \times 2l$   
identity)

Recalling  
that  $Y \geq 0$ ,

can pick  $B = \sqrt{Y} O$

w/ ~~l~~

for some ~~orthogonal~~ matrix  $O$ ,

w/ orthonormal rows ( $2m \times 2l$ )

Then reduced evolution is matrix

Set  $l = 2m$

$$A \sigma A^T + B \sigma_E B^T$$

$$= X \sigma X^T + \sqrt{Y} O I O^T \sqrt{Y}$$

$$= X \sigma X^T + Y$$

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So we need to figure out  
how to pick  $C$  &  $D$   
such that  $S$  is symplectic.

Previously, we showed that symplectic  
condition  $S \Omega S^T = \Omega$  is  
equivalent to

$$A \Omega_n A^T + B \Omega_l B^T = \Omega_m, \quad (*)$$

$$A \Omega_n C^T + B \Omega_l D^T = 0,$$

$$C \Omega_n A^T + D \Omega_l B^T = 0,$$

$$C \Omega_n C^T + D \Omega_l D^T = \Omega_{n+l-m}$$

Then ~~the~~ matrix  $O$  should  
be chosen such that  $(*)$   
is satisfied, i.e.,

$$X \Omega_n X^T + \sqrt{Y} O \Omega_l O^T \sqrt{Y} = \Omega_m$$



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For simplicity, consider the case  
of pos. definite  $Y > 0$ .

Then rewrite condition as

$$O\Omega_2 O^T = Y^{-1/2} (\Omega_m - X\Omega_n X^T) Y^{-1/2}$$

This matrix is  
antisymmetric

It thus can be brought into  
canonical form by orthogonal  
 $2m \times 2m$  matrix  $R$

$$R Y^{-1/2} (\Omega_m - X\Omega_n X^T) Y^{-1/2} R^T \\ = \bigoplus_{j=1}^m d_j \Omega_1$$

the condition

$$Y + i\Omega_m \geq iX\Omega_n X^T \Leftrightarrow$$

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$$Y \geq i\Omega_m - iX\Omega_n X^T \quad (\text{by moving around } \& \text{ transpose})$$

$$\Leftrightarrow I \geq Y^{-1/2} (i\Omega_m - iX\Omega_n X^T) Y^{-1/2}$$

$$\Rightarrow d_j \leq 1 \quad \forall j$$

Now consider that by setting

$$O_j = \begin{pmatrix} \cos \theta_j & 0 & -\sin \theta_j & 0 \\ 0 & \cos \theta_j & 0 & \sin \theta_j \end{pmatrix}$$

~~such~~ such that  $\cos(2\theta_j) = d_j$ ,

we find that

$$O_j O_j^T = I_2 \quad O_j \Omega_2 O_j^T = \begin{bmatrix} 0 & d_j \\ -d_j & 0 \end{bmatrix}$$

$$\Rightarrow M = \bigoplus_{j=1}^m O_j \quad \text{is s.t.}$$

$$M \Omega_e M^T = R Y^{-1/2} (\Omega_m - X \Omega_n X^T) Y^{-1/2} \quad R^T$$

(10)

Note that  $M$  has form

$$M = \begin{bmatrix} \underline{0}_1 & \underline{0} & \underline{0} & \underline{0} \\ \underline{0} & \underline{0}_2 & & \\ \vdots & & \ddots & \\ \underline{0} & & & \underline{0}_m \end{bmatrix}$$

Then set  $O = R^T M \phi$

$$\Rightarrow O \Omega_e O^T = Y^{-1/2} (\Omega_m - X \Omega_n X^T) Y^{-1/2}$$

So then we have  $A \phi B$

$$\text{s.t. } A = X \quad \phi \quad B = \sqrt{Y} O \quad (\Rightarrow \begin{matrix} B B^T \\ = Y \end{matrix})$$

$$\phi \quad A \Omega_n A^T + B \Omega_e B^T = \Omega_m$$

- can restate the latter condition as saying that the rows ~~of~~  $v_j$  the matrix  $[A \ B]$

$$\text{satisfy } v_j \Omega_{m+(n+m)} v_k^T = \Omega_{jk}$$

$$\text{where } \Omega_{m+(n+m)} = \begin{bmatrix} \Omega_m & \underline{0} \\ \underline{0} & \Omega_{n+m} \end{bmatrix}$$

(11)

The remainder of the proof  
is regarding ~~extending~~ finding  
matrices  $C$  &  $D$  such  
that

$$S = \begin{bmatrix} A & B \\ C & D \end{bmatrix} \text{ is a}$$

symplectic matrix.

- This is equivalent to extending the  
symplectic basis formed by the rows  
of  $[A \ B]$  to a complete  
symplectic basis for the  $m+n+m$   
space. Already have  $m$  linearly  
independent vectors

- Procedure consists of finding  
 $n+m$  other linearly independent  
vectors & performing a symplectic  
Gram-Schmidt orthogonalization

(12)

Some special cases of channels:

1) unitary evolution + noise

Suppose that  $X$  is symplectic so that  $n=m$ .

Then condition

$$iX^* \Omega_n X^T + Y \geq i \Omega_n$$

becomes

$$i \Omega_n + Y \geq i \Omega_n$$

$\Rightarrow Y \geq 0$  & channel

can be thought of as the composition of unitary evolution according to symp. matrix  $X$  followed by

additive noise according to  $Y$ .

(13)

Action of the adjoint of a Gaussian channel on displacement operators:

Let  $\mathcal{N}$  be a Gaussian channel characterized by  $X$  &  $Y$ .

then

$$\mathcal{N}^\dagger(\hat{D}_{\underline{r}}) = \hat{D}_{\underline{r}X^T} e^{-\frac{1}{4}\underline{r}^T Y \underline{r}}$$

Proof: For arbitrary operator  $\hat{A}$ , Gaussian Stinespring dilation allows for writing

$$\mathcal{N}(\hat{A}) = \text{Tr}_E \left[ \hat{S}^\dagger (\hat{A} \otimes |0\rangle\langle 0|) \hat{S} \right]$$

for Gaussian unitary  $\hat{S}$  w/ symp. transformation  $S$  satisfying

(14)

$$\hat{S} \hat{R} \hat{S}^\dagger = S \hat{R}$$

( $\hat{R}$  is vector  
of canonical  
op's for  
bipartite  
system)

$$\hat{S} \hat{D}_R \hat{S}^\dagger = \hat{D}_{S^{-1}R}$$

$R$  is  
real vector.

$S$  can be written in block form as

$$S = \begin{pmatrix} X & \sqrt{Y} 0 \\ * & * \end{pmatrix}$$

Then, from the definition of adjoint, it follows that

$$N^+(\hat{B}) = \text{Tr}_E \left[ (I \otimes |0\rangle\langle 0|) \hat{S} (\hat{B} \otimes I) \hat{S}^\dagger \right]$$

then set  $\hat{B} = \hat{D}_{Rr}$  to find that

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$$\begin{aligned} & \chi^+(\hat{D}\underline{r}) \\ &= \text{Tr}_E \left[ (\mathbb{I} \otimes |0\rangle\langle 0|) \hat{S} (\hat{D}\underline{r} \otimes \hat{\mathbb{I}}) \hat{S}^\dagger \right] \\ &= \text{Tr}_E \left[ (\mathbb{I} \otimes |0\rangle\langle 0|) \hat{S} \hat{D}\underline{r} (\mathbb{I} \otimes |0\rangle\langle 0|) \hat{S}^\dagger \right] \\ &= \text{Tr}_E \left[ (\mathbb{I} \otimes |0\rangle\langle 0|) \hat{D} \underline{S}^{-1} \underline{r} (\mathbb{I} \otimes |0\rangle\langle 0|) \right] \\ &= \text{Tr}_E \left[ (\mathbb{I} \otimes |0\rangle\langle 0|) \hat{D} \underline{r} \underline{S}^T (\mathbb{I} \otimes |0\rangle\langle 0|) \right] \\ &= \text{Tr}_E \left[ (\mathbb{I} \otimes |0\rangle\langle 0|) \hat{D} \underline{r} \underline{X}^T \underline{r} \otimes \underline{r} \underline{r}^T \underline{Y} \right] \\ &= \hat{D} \underline{r} \underline{X}^T \underline{r} \text{Tr} \left[ |0\rangle\langle 0| \hat{D} \underline{r} \underline{r}^T \underline{Y} \right] \\ &= \hat{D} \underline{r} \underline{X}^T \underline{r} \chi_{|0\rangle\langle 0|}(\underline{r} \underline{r}^T \underline{Y}) \end{aligned}$$

Now using that  $\chi_{|0\rangle\langle 0|}(\underline{r}) = e^{-\frac{1}{4}|\underline{r}|^2}$

$$= \hat{D} \underline{r} \underline{X}^T \underline{r} e^{-\frac{1}{4}|\underline{r} \underline{r}^T \underline{Y}|^2}$$

$$= \hat{D} \underline{r} \underline{X}^T \underline{r} e^{-\frac{1}{4}\underline{r}^T \underline{Y} \underline{r}}$$